# POSITIVE PERIODIC SOLUTIONS OF A NEUTRAL FUNCTIONAL DIFFERENTIAL EQUATION WITH MULTIPLE DELAYS 

Yongxiang Li, Ailan Liu, Lanzhou<br>Received April 11, 2016. First published May 18, 2017.<br>Communicated by Jiří Šremr

Abstract. This paper deals with the existence of positive $\omega$-periodic solutions for the neutral functional differential equation with multiple delays

$$
(u(t)-c u(t-\delta))^{\prime}+a(t) u(t)=f\left(t, u\left(t-\tau_{1}\right), \ldots, u\left(t-\tau_{n}\right)\right)
$$

The essential inequality conditions on the existence of positive periodic solutions are obtained. These inequality conditions concern with the relations of $c$ and the coefficient function $a(t)$, and the nonlinearity $f\left(t, x_{1}, \ldots, x_{n}\right)$. Our discussion is based on the perturbation method of positive operator and fixed point index theory in cones.

Keywords: neutral delay differential equation; positive periodic solution; cone; fixed point index

MSC 2010: 34K13, 34K40, 47H11

## 1. Introduction

In the paper, we discuss the existence of positive $\omega$-periodic solutions of the neutral functional differential equation with multiple delays

$$
\begin{equation*}
(u(t)-c u(t-\delta))^{\prime}+a(t) u(t)=f\left(t, u\left(t-\tau_{1}\right), \ldots, u\left(t-\tau_{n}\right)\right) \tag{1.1}
\end{equation*}
$$

where $\delta>0,|c|<1$ are constants, $a \in C(\mathbb{R},(0, \infty))$ is a $\omega$-periodic function, $f: \mathbb{R} \times$ $[0, \infty)^{n} \rightarrow[0, \infty)$ is a continuous function which is $\omega$-periodic in $t$, and $\tau_{1}, \tau_{2}, \ldots, \tau_{n}$ are positive constants.

The research has been supported by NNSFs of China (No. 11661071, 11261053, 11361055) and the NSF of Gansu Province (No.1208RJZA129).

The delay differential equation has been proposed in many fields such as biology, physicochemistry, mechanics and economics, see [4], [7]. The existence problems of periodic solutions have attracted many authors' attention, see [2], [5], [6], [8]-[12] and references therein. In some practice models, only positive periodic solutions are significant. In [11], [12], the authors obtained the existence of positive periodic solutions for some delay first-order differential equations in the form of

$$
\begin{equation*}
u^{\prime}(t)+a(t) u(t)=f(t, u(t-\tau(t))) \tag{1.2}
\end{equation*}
$$

by employing the fixed point theorem of cone mapping, and one well-known result is that if the nonlinearity $f(t, x)$ has superlinear or sublinear growth on $x$, the equation (1.2) has at least one positive $\omega$-periodic solution.

Among the previous works, there are few ones concerned with neutral differential equations. In [10], by means of the continuation theorem of coincidence degree principle, Serra discussed the existence of periodic solutions for the neutral differential equation

$$
\begin{equation*}
(u(t)-c u(t-\delta))^{\prime}=f(t, u(t)) . \tag{1.3}
\end{equation*}
$$

In [8], Luo, Wang and Shen employed the Krasnoselskii fixed point theorem on the sum of a compact operator and a contractive operator to obtain the existence of positive periodic solutions for the neutral functional differential equation with delay

$$
\begin{equation*}
(u(t)-c u(t-\tau(t)))^{\prime}+a(t) u(t)=f(t, u(t-\tau(t))) . \tag{1.4}
\end{equation*}
$$

Motivated by the papers mentioned above, we study the existence of positive periodic solutions of the neutral functional differential equation (1.1) with multiple delays. We aim to obtain the essential conditions on the existence of positive periodic solutions of equation (1.1) via the theory of the fixed point index in cones. Specially, we hope the well-known existence result for equation (1.2) holds for equation (1.1). We will show that if $c$ and $a(t)$ satisfy the following restriction condition (H), the result is true for equation (1.1).

For convenience, we introduce the notations

$$
\begin{equation*}
\underline{a}=\min _{0 \leqslant t \leqslant \omega} a(t), \quad \bar{a}=\max _{0 \leqslant t \leqslant \omega} a(t), \quad \sigma=\exp \left(-2 \int_{0}^{\omega} a(r) \mathrm{d} r\right) \tag{1.5}
\end{equation*}
$$

and make the following assumption:

$$
\begin{equation*}
|c|<\frac{\sigma}{\sigma+1} . \tag{H}
\end{equation*}
$$

Our main results are as follows:

Theorem 1.1. Let $a \in C(\mathbb{R},(0, \infty))$ be a $\omega$-periodic function, $c$ satisfy assumption (H), $f \in C\left(\mathbb{R} \times[0, \infty)^{n},[0, \infty)\right)$ and $f\left(t, x_{1}, \ldots, x_{n}\right)$ be $\omega$-periodic in $t$. If $f$ satisfies the conditions
(F1) there exist positive constants $c_{1}, \ldots, c_{n}$ satisfying $c_{1}+\ldots+c_{n}<\underline{a}$ and $\eta>0$ such that

$$
f\left(t, x_{1}, \ldots, x_{n}\right) \leqslant c_{1} x_{1}+\ldots+c_{n} x_{n}
$$

for $t \in \mathbb{R}$ and $x_{1}, \ldots, x_{n} \in[0, \eta]$;
(F2) there exist positive constants $d_{1}, \ldots, d_{n}$ satisfying $d_{1}+\ldots+d_{n}>\bar{a}$ and $H>0$ such that

$$
f\left(t, x_{1}, \ldots, x_{n}\right) \geqslant d_{1} x_{1}+\ldots+d_{n} x_{n}
$$

for $t \in \mathbb{R}$ and $x_{1}, \ldots, x_{n} \geqslant H$,
then equation (1.1) has at least one positive $\omega$-periodic solution.

Theorem 1.2. Let $a \in C(\mathbb{R},(0, \infty))$ be a $\omega$-periodic function, $c$ satisfy assumption (H), $f \in C\left(\mathbb{R} \times[0, \infty)^{n},[0, \infty)\right)$ and $f\left(t, x_{1}, \ldots, x_{n}\right)$ be $\omega$-periodic in $t$. If $f$ satisfies the conditions
(F3) there exist positive constants $d_{1}, \ldots, d_{n}$ satisfying $d_{1}+\ldots+d_{n}>\bar{a}$ and $\eta>0$ such that

$$
f\left(t, x_{1}, \ldots, x_{n}\right) \geqslant d_{1} x_{1}+\ldots+d_{n} x_{n}
$$

for $t \in \mathbb{R}$ and $x_{1}, \ldots, x_{n} \in[0, \eta]$;
(F4) there exist positive constants $c_{1}, \ldots, c_{n}$ satisfying $c_{1}+\ldots+c_{n}<\underline{a}$ and $H>0$ such that

$$
f\left(t, x_{1}, \ldots, x_{n}\right) \leqslant c_{1} x_{1}+\ldots+c_{n} x_{n}
$$

for $t \in \mathbb{R}$ and $x_{1}, \ldots, x_{n} \geqslant H$,
then equation (1.1) has at least one positive $\omega$-periodic solution.
In Theorem 1.1, conditions (F1) and (F2) allow $f\left(t, x_{1}, \ldots, x_{n}\right)$ to have superlinear growth on $x_{1}, \ldots, x_{n}$. For example,

$$
f\left(t, x_{1}, \ldots, x_{n}\right)=a_{1}(t) x_{1}^{2}+\ldots+a_{n}(t) x_{n}^{2}
$$

satisfies (F1) and (F2), where $a_{1}(t), \ldots, a_{n}(t)$ are positive and continuous $\omega$-periodic functions.

In Theorem 1.2, conditions (F3) and (F4) allow $f\left(t, x_{1}, \ldots, x_{n}\right)$ to have sublinear growth on $x_{1}, \ldots, x_{n}$. For example,

$$
f\left(t, x_{1}, \ldots, x_{n}\right)=b_{1}(t) \sqrt{\left|x_{1}\right|}+\ldots+b_{n}(t) \sqrt{\left|x_{n}\right|}
$$

satisfies (F3) and (F4), where $b_{1}(t), \ldots, b_{n}(t)$ are positive and continuous $\omega$-periodic functions.

Conditions (F1) and (F2) in Theorem 1.1 and conditions (F3) and (F4) in Theorem 1.2 are optimal for the existence of positive periodic solutions of equation (1.1). This fact can be shown from the neutral differential equation with linear delays

$$
\begin{equation*}
(u(t)-c u(t-\delta))^{\prime}+a_{0} u(t)=a_{1} u\left(t-\tau_{1}\right)+\ldots+a_{n} u\left(t-\tau_{n}\right)+h(t) \tag{1.6}
\end{equation*}
$$

where $a_{0}, a_{1}, \ldots, a_{n}$ are positive constants, $h \in C(\mathbb{R})$ is a positive $\omega$-periodic function. If $a_{1}, \ldots, a_{n}$ satisfy

$$
\begin{equation*}
a_{1}+a_{2}+\ldots+a_{n}=a_{0} \tag{1.7}
\end{equation*}
$$

equation (1.6) has no positive $\omega$-periodic solutions. In fact, if equation (1.6) has a positive $\omega$-periodic solution, integrating the equation on $[0, \omega]$ and using the periodicity of $u(t)$, we can obtain that $\int_{0}^{\omega} h(t) \mathrm{d} t=0$, which contradicts the positivity of $h(t)$. Hence, equation (1.6) has no positive $\omega$-periodic solution. For $a(t) \equiv a_{0}$ and $f\left(t, x_{1}, \ldots, x_{n}\right)=a_{1} x_{1}+\ldots+a_{n} x_{n}+h(t)$, if condition (1.7) holds, conditions (F1) and (F2) in Theorem 1.1 and conditions (F3) and (F4) in Theorem 1.2 are not satisfied. From this we see that the conditions in Theorems 1.1-1.2 are optimal.

The proofs of Theorems 1.1 and 1.2 are based on the fixed point index theory in cones, which will be given in Section 3. Some preliminaries to discuss equation (1.1) are presented in Section 2.

## 2. Preliminaries

Let $C_{\omega}(\mathbb{R})$ denote the Banach space of all continuous $\omega$-periodic functions $u(t)$ with norm $\|u\|_{C}=\max _{0 \leqslant t \leqslant \omega}|u(t)|$. Let $C_{\omega}^{1}(\mathbb{R})$ be the continuous differentiable $\omega$-periodic function space and $C_{\omega}^{+}(\mathbb{R})$ be the cone of all nonnegative functions in $C_{\omega}(\mathbb{R})$.

In order to discuss the existence of positive $\omega$-periodic solutions of equation (1.1), we need to build the existence and uniqueness results of $\omega$-periodic solutions for the corresponding linear neutral differential equation

$$
\begin{equation*}
(u(t)-c u(t-\delta))^{\prime}+a(t) u(t)=h(t), \quad t \in \mathbb{R} \tag{2.1}
\end{equation*}
$$

where $h \in C_{\omega}(\mathbb{R})$. For this we consider the linear differential equation

$$
\begin{equation*}
u^{\prime}(t)+2 a(t) u(t)=h(t), \quad t \in \mathbb{R} . \tag{2.2}
\end{equation*}
$$

By a direct calculation, we easily prove that for every $h \in C_{\omega}(\mathbb{R})$ equation (2.2) has a unique $\omega$-periodic solution given by

$$
\begin{equation*}
u(t)=\int_{t}^{t+\omega} G(t, s) h(s) \mathrm{d} s:=\operatorname{Th}(t) \tag{2.3}
\end{equation*}
$$

where

$$
\begin{equation*}
G(t, s)=\frac{\exp \left(2 \int_{t}^{s} a(r) \mathrm{d} r\right)}{\exp \left(2 \int_{0}^{\omega} a(r) \mathrm{d} r\right)-1} \tag{2.4}
\end{equation*}
$$

Clearly, the operator $T: C(\mathbb{R}) \rightarrow C(\mathbb{R})$ defined by (2.3) is a completely continuous linear operator.

Define a subcone $K_{0}$ of $C_{\omega}^{+}(\mathbb{R})$ in $C_{\omega}(\mathbb{R})$ by

$$
\begin{equation*}
K_{0}=\left\{u \in C_{\omega}(\mathbb{R}): u(t) \geqslant \sigma\|u\|_{C}, t \in \mathbb{R}\right\} \tag{2.5}
\end{equation*}
$$

Lemma 2.1. For every $h \in C_{\omega}^{+}(\mathbb{R})$, the $\omega$-periodic solution of equation (2.2), $u=T h \in K_{0}$. Namely, $T\left(C_{\omega}^{+}(\mathbb{R})\right) \subset K_{0}$.

Proof. By the expression (2.4) of the Green function $G(t, s)$,

$$
\begin{align*}
& \bar{G}:=\max \{G(t, s): t \in \mathbb{R}, t \leqslant s \leqslant t+\omega\}=\frac{\exp \left(2 \int_{0}^{\omega} a(r) \mathrm{d} r\right)}{\exp \left(2 \int_{0}^{\omega} a(r) \mathrm{d} r\right)-1},  \tag{2.6}\\
& \underline{G}:=\min \{G(t, s): t \in \mathbb{R}, t \leqslant s \leqslant t+\omega\}=\frac{1}{\exp \left(2 \int_{0}^{\omega} a(r) \mathrm{d} r\right)-1}
\end{align*}
$$

Let $h \in C_{\omega}^{+}(\mathbb{R})$ and $u=T h$. For every $t \in \mathbb{R}$, from (2.3) it follows that

$$
u(t)=\int_{t}^{t+\omega} G(t, s) h(s) \mathrm{d} s \leqslant \bar{G} \int_{t}^{t+\omega} h(s) \mathrm{d} s=\bar{G} \int_{0}^{\omega} h(s) \mathrm{d} s
$$

and therefore,

$$
\|u\|_{C} \leqslant \bar{G} \int_{0}^{\omega} h(s) \mathrm{d} s
$$

Noting that $\underline{G} / \bar{G}=\sigma$, by (2.3) we obtain that

$$
u(t)=\int_{t}^{t+\omega} G(t, s) h(s) \mathrm{d} s \geqslant \underline{G} \int_{t}^{t+\omega} h(s) \mathrm{d} s=\underline{G} \int_{0}^{\omega} h(s) \mathrm{d} s \geqslant \sigma\|u\|_{C} .
$$

Hence, $T h=u \in K_{0}$.

Let $A: C_{\omega}(\mathbb{R}) \rightarrow C_{\omega}(\mathbb{R})$ be the linear bounded operator defined by

$$
\begin{equation*}
A u(t)=u(t)-c u(t-\delta), \quad t \in \mathbb{R}, u \in C_{\omega}(\mathbb{R}) \tag{2.7}
\end{equation*}
$$

We easily verify the following lemma:

Lemma 2.2. If $|c|<1$, then $A$ has a bounded inverse operator $A^{-1}$ : $C_{\omega}(\mathbb{R}) \rightarrow C_{\omega}(\mathbb{R})$, which is given by

$$
\begin{equation*}
A^{-1} v(t)=\sum_{j=0}^{\infty} c^{j} v(t-j \delta), \quad v \in C_{\omega}(\mathbb{R}) \tag{2.8}
\end{equation*}
$$

and its norm satisfies $\left\|A^{-1}\right\| \leqslant 1 /(1-|c|)$.
Let $v=A u$. Then equation (2.1) becomes

$$
\begin{equation*}
v^{\prime}(t)+a(t) A^{-1} v(t)=h(t), \quad t \in \mathbb{R} . \tag{2.9}
\end{equation*}
$$

From (2.8) we easily verify that if $v \in C_{\omega}^{1}(\mathbb{R})$, then $A^{-1} v \in C_{\omega}^{1}(\mathbb{R})$ and $\left(A^{-1} v\right)^{\prime}=$ $A^{-1} v^{\prime}$. Hence, $u \in C_{\omega}^{1}(\mathbb{R})$ is a $\omega$-periodic solution of equation (2.1) if and only if $v=A u \in C_{\omega}^{1}(\mathbb{R})$ is a $\omega$-periodic solution of equation (2.9).

Lemma 2.3. If $|c|<\frac{1}{2}$, then for every $h \in C_{\omega}(\mathbb{R})$, equation (2.9) has a unique $\omega$-periodic solution $v \in C_{\omega}^{1}(\mathbb{R})$. Furthermore, for $h \in C_{\omega}^{+}(\mathbb{R})$, the solution $v \in K_{0}$ when $|c|<\sigma /(\sigma+1)$.

Proof. Rewrite equation (2.9) to the form of

$$
\begin{equation*}
v^{\prime}(t)+2 a(t) v(t)=B v(t)+h(t), \quad t \in \mathbb{R} \tag{2.10}
\end{equation*}
$$

where $B: C_{\omega}(\mathbb{R}) \rightarrow C_{\omega}(\mathbb{R})$ is a linear bounded operator defined by

$$
\begin{align*}
B v(t) & =2 a(t) v(t)-a(t) A^{-1} v(t)  \tag{2.11}\\
& =a(t) v(t)+a(t)\left(I-A^{-1}\right) v(t) \\
& =a(t) v(t)-c a(t) A^{-1} v(t-\delta), \quad t \in \mathbb{R} .
\end{align*}
$$

From (2.10) it is easy to see that the $\omega$-periodic solution problem of equation (2.9) is equivalent to the operator equation in Banach space $C_{\omega}(\mathbb{R})$

$$
\begin{equation*}
(I-T B) v=T h \tag{2.12}
\end{equation*}
$$

where $T: C_{\omega}(\mathbb{R}) \rightarrow C_{\omega}(\mathbb{R})$ is the $\omega$-periodic solution operator of equation (2.2) given by (2.3), $I$ is the identity operator in $C_{\omega}(\mathbb{R})$. We prove that the norm of $T B$ in $\mathcal{L}\left(C_{\omega}(\mathbb{R}), C_{\omega}(\mathbb{R})\right)$ satisfies $\|T B\|<1$.

For every $v \in C_{\omega}(\mathbb{R})$, by the definition of $B$ we have

$$
\begin{aligned}
|B v(t)| & =\left|a(t) v(t)-c a(t) A^{-1} v(t-\delta)\right| \\
& \leqslant a(t)\|v\|_{C}+|c| a(t)\left\|A^{-1} v\right\|_{C} \leqslant\left(1+\frac{|c|}{1-|c|}\right)\|v\|_{C} a(t)
\end{aligned}
$$

By this and the definition (2.3) of $T$ and the positivity of $G(t, s)$, we have

$$
\begin{aligned}
|T B v(t)| & \leqslant \int_{t}^{t+\omega} G(t, s)|B v(s)| \mathrm{d} s \\
& \leqslant\left(1+\frac{|c|}{1-|c|}\right)\|v\|_{C} \int_{t-\omega}^{t} G(t, s) a(s) \mathrm{d} s=\frac{1}{2}\left(1+\frac{|c|}{1-|c|}\right)\|v\|_{C}
\end{aligned}
$$

from which it follows that $\|T B v\|_{C} \leqslant \frac{1}{2}(1+|c| /(1-|c|))\|v\|_{C}$. Therefore,

$$
\begin{equation*}
\|T B\| \leqslant \frac{1}{2}\left(1+\frac{|c|}{1-|c|}\right) \tag{2.13}
\end{equation*}
$$

Since $|c|<\frac{1}{2}$, it follows that

$$
\frac{1}{2}\left(1+\frac{|c|}{1-|c|}\right)<1
$$

By this inequality and (2.13), we obtain that $\|T B\|<1$.
Thus, $I-T B$ has a bounded inverse operator given by the series

$$
(I-T B)^{-1}=\sum_{n=0}^{\infty}(T B)^{n}
$$

Consequently, equation (2.12), equivalently equation (2.9), has a unique $\omega$-periodic solution

$$
\begin{equation*}
v=(I-T B)^{-1} T h=\sum_{n=0}^{\infty}(T B)^{n} T h . \tag{2.14}
\end{equation*}
$$

For $h \in C_{\omega}^{+}(\mathbb{R})$, let $w=T h$. By Lemma 2.1, $w \in K_{0}$. Hence we have

$$
\begin{aligned}
B w(t) & =a(t) w(t)-c a(t) A^{-1} w(t-\delta) \\
& \geqslant a(t) w(t)-|c| a(t)\left\|A^{-1} w\right\|_{C} \\
& \geqslant a(t) \sigma\|w\|_{C}-a(t)|c|\left\|A^{-1} w\right\|_{C} \\
& \geqslant a(t)\left(\sigma-\frac{|c|}{1-|c|}\right)\|w\|_{C}
\end{aligned}
$$

Hence, when $|c|<\sigma /(\sigma+1), B w(t) \geqslant 0$ for every $t \in \mathbb{R}$. Namely, $B w \in C_{\omega}^{+}(\mathbb{R})$. By Lemma 2.1, (TB) $w=T(B w) \in K_{0}$. Using the inductive method we easily prove that $(T B)^{n} w \in K_{0}$ for every $n \in \mathbb{N}$. Thus according to (2.14), the unique $\omega$-periodic solution of equation (2.9) is

$$
v=\sum_{n=0}^{\infty}(T B)^{n} T h=\sum_{n=0}^{\infty}(T B)^{n} w \in K_{0} .
$$

This completes the proof of Lemma 2.3.
Let $c$ satisfy assumption (H). Choose a positive constant $\alpha$ as

$$
\alpha= \begin{cases}\sigma(1-|c|), & \text { if } c \geqslant 0  \tag{2.15}\\ \frac{\sigma-|c|}{1+|c|}, & \text { if } c<0\end{cases}
$$

and define another cone $K$ in $C_{\omega}(\mathbb{R})$ by

$$
\begin{equation*}
K=\left\{u \in C_{\omega}(\mathbb{R}): u(t) \geqslant \alpha\|u\|_{C}, t \in \mathbb{R}\right\} . \tag{2.16}
\end{equation*}
$$

Lemma 2.4. If $c$ satisfies assumption $(H)$, then for every $h \in C_{\omega}(\mathbb{R})$, equation (2.1) has a unique $\omega$-periodic solution $u:=S h \in C_{\omega}^{1}(\mathbb{R})$. Moreover, $S$ : $C_{\omega}(\mathbb{R}) \rightarrow C_{\omega}(\mathbb{R})$ is a completely continuous linear operator, and $S h \in K$ when $h \in C_{\omega}^{+}(\mathbb{R})$.

Proof. Let $h \in C_{\omega}(\mathbb{R})$. By assumption (H) and Lemma 2.3, equation (2.9) has a unique $\omega$-periodic solution $v \in C_{\omega}^{1}(\mathbb{R})$ given by (2.14). Hence

$$
\begin{equation*}
u=A^{-1} v=A^{-1}(I-T B)^{-1} T h:=S h \tag{2.17}
\end{equation*}
$$

is a unique $\omega$-periodic solution of equation (2.1), where

$$
\begin{equation*}
S=A^{-1}(I-T B)^{-1} T \tag{2.18}
\end{equation*}
$$

is the corresponding $\omega$-periodic solution operator. In (2.18), since

$$
(I-T B)^{-1} T=\sum_{n=0}^{\infty}(T B)^{n} T=T\left(I+B\left(\sum_{n=0}^{\infty}(T B)^{n} T\right)\right)
$$

from the complete continuity of operator $T: C_{\omega}(\mathbb{R}) \rightarrow C_{\omega}(\mathbb{R})$ and boundedness of operator $I+B\left(\sum_{n=0}^{\infty}(T B)^{n} T\right): C_{\omega}(\mathbb{R}) \rightarrow C_{\omega}(\mathbb{R})$, it follows that $(I-T B)^{-1} T$ : $C_{\omega}(\mathbb{R}) \rightarrow C_{\omega}(\mathbb{R})$ is a completely continuous linear operator. Combining this with
the fact that $A^{-1}: C_{\omega}(\mathbb{R}) \rightarrow C_{\omega}(\mathbb{R})$ is a bounded linear operator, we see that $S=$ $A^{-1}(I-T B)^{-1} T: C_{\omega}(\mathbb{R}) \rightarrow C_{\omega}(\mathbb{R})$ is completely continuous.

Let $h \in C_{\omega}^{+}(\mathbb{R})$ and $u=S h$. By Lemma 2.3, equation (2.9) has a unique $\omega$-periodic solution $v \in K_{0}$. By (2.17), $u=A^{-1} v$.

If $c \geqslant 0$, by Lemma 2.2 and the definition of cone $K_{0}$, we have

$$
\begin{aligned}
u(t) & =A^{-1} v(t)=\sum_{j=0}^{\infty} c^{j} v(t-j \delta) \geqslant v(t) \geqslant \sigma\|v\|_{C}=\sigma\|A u\|_{C} \\
& \geqslant \sigma\left\|A^{-1}\right\|^{-1}\|u\|_{C}=\sigma(1-|c|)\|u\|_{C}=\alpha\|u\|_{C}
\end{aligned}
$$

If $c<0$, by Lemma 2.2 and the definition of cone $K_{0}$, we have

$$
\begin{aligned}
u(t) & =A^{-1} v(t)=\sum_{j=0}^{\infty} c^{j} v(t-j \delta) \\
& =\sum_{j=0}^{\infty}|c|^{2 j} v(t-2 j \delta)-\sum_{j=0}^{\infty}|c|^{2 j+1} v(t-(2 j+1) \delta) \\
& \geqslant \sum_{j=0}^{\infty}|c|^{2 j} \sigma\|v\|_{C}-\sum_{j=0}^{\infty}|c|^{2 j+1}\|v\|_{C} \\
& =\frac{\sigma-|c|}{1-|c|^{2}}\|v\|_{C}=\frac{\sigma-|c|}{1-|c|^{2}}\|A u\|_{C} \\
& \geqslant \frac{\sigma-|c|}{1-|c|^{2}}\left\|A^{-1}\right\|^{-1}\|u\|_{C}=\frac{\sigma-|c|}{1+|c|}\|u\|_{C}=\alpha\|u\|_{c}
\end{aligned}
$$

Hence $S h=u \in K$.
Let $f \in C\left(\mathbb{R} \times[0, \infty)^{n},[0, \infty)\right)$. Now we consider the nonlinear equation (1.1). For every $u \in K$, set

$$
\begin{equation*}
F(u)(t):=f\left(t, u\left(t-\tau_{1}\right), \ldots, u\left(t-\tau_{n}\right)\right), \quad t \in \mathbb{R} \tag{2.19}
\end{equation*}
$$

Then $F: K \rightarrow C_{\omega}^{+}(\mathbb{R})$ is continuous. Define a mapping $Q: K \rightarrow K$ by

$$
\begin{equation*}
Q(u)=S(F(u)), \quad u \in K \tag{2.20}
\end{equation*}
$$

By the definition of operator $S$, the positive $\omega$-periodic solution of equation (1.1) is equivalent to the nontrivial fixed point of $Q$. By Lemma 2.4, we have the following statement:

Lemma 2.5. $Q: K \rightarrow K$ is a completely continuous mapping.

We will find the nonzero fixed point of $Q$ by using the fixed point index theory in cones. The following two lemmas from [1], [3] are needed in our argument.

Lemma 2.6. Let $E$ be a Banach space, $\Omega$ be a bounded open subset of $E$ with $\theta \in \Omega, Q: K \cap \bar{\Omega} \rightarrow K$ a completely continuous mapping. If $\lambda Q(u) \neq u$ for every $u \in K \cap \partial \Omega$ and $0<\lambda \leqslant 1$, then the fixed point index $i(Q, K \cap \Omega, K)=1$.

Lemma 2.7. Let $E$ be a Banach space, $\Omega$ be a bounded open subset of $E$ and $Q: K \cap \bar{\Omega} \rightarrow K$ a completely continuous mapping. If there exists an $e \in K \backslash\{\theta\}$ such that $u-Q(u) \neq \mu e$ for every $u \in K \cap \partial \Omega$ and $\mu \geqslant 0$, then the fixed point index $i(Q, K \cap \Omega, K)=0$.

In the next section, we will use Lemma 2.6 and Lemma 2.7 to prove Theorem 1.1 and Theorem 1.2.

## 3. Proofs of main results

Pro of of Theorem 1.1. Choose $E=C_{\omega}(\mathbb{R})$. Let $K \subset E$ be the closed convex cone defined by (2.16) and $Q: K \rightarrow K$ be the operator defined by (2.20). Then the positive $\omega$-periodic solution of equation (1.1) is equivalent to the nontrivial fixed point of $Q$. Set

$$
\begin{equation*}
\Omega_{1}=\left\{u \in C_{\omega}(\mathbb{R}):\|u\|_{C}<r\right\}, \quad \Omega_{2}=\left\{u \in C_{\omega}(\mathbb{R}):\|u\|_{C}<R\right\} \tag{3.1}
\end{equation*}
$$

where $0<r<R<\infty$. We show that the operator $Q$ has a fixed point in $K \cap\left(\Omega_{2} \backslash \bar{\Omega}_{1}\right)$ when $r$ is small enough and $R$ large enough.

Let $r \in(0, \eta)$, where $\eta$ is the positive constant in condition (F1). We prove that $Q$ satisfies the condition of Lemma 2.6 in $K \cap \partial \Omega_{1}$, namely $\lambda Q u \neq u$ for every $u \in K \cap \partial \Omega_{1}$ and $0<\lambda \leqslant 1$. In fact, if there exist $u_{0} \in K \cap \partial \Omega_{1}$ and $0<\lambda_{0} \leqslant 1$ such that $\lambda_{0} Q u_{0}=u_{0}$, then by the definition of $Q$ and Lemma 2.4, $u_{0} \in C_{\omega}^{1}(\mathbb{R})$ satisfies the delay differential equation

$$
\begin{equation*}
\left(u_{0}(t)-c u_{0}(t-\delta)\right)^{\prime}+a(t) u_{0}(t)=\lambda_{0} f\left(t, u_{0}\left(t-\tau_{1}\right), \ldots, u_{0}\left(t-\tau_{n}\right)\right), \quad t \in \mathbb{R} . \tag{3.2}
\end{equation*}
$$

Since $u_{0} \in K \cap \partial \Omega_{1}$, by the definitions of $K$ and $\Omega_{1}$, we have

$$
\begin{equation*}
0 \leqslant u_{0}\left(t-\tau_{k}\right) \leqslant\left\|u_{0}\right\|_{C}=r<\eta, \quad k=1, \ldots, n, t \in \mathbb{R} . \tag{3.3}
\end{equation*}
$$

Hence from condition (F1) it follows that

$$
f\left(t, u_{0}\left(t-\tau_{1}\right), \ldots, u_{0}\left(t-\tau_{n}\right)\right) \leqslant c_{1} u_{0}\left(t-\tau_{1}\right)+\ldots+c_{n} u_{0}\left(t-\tau_{n}\right), \quad t \in \mathbb{R}
$$

By this and (3.2), we obtain that

$$
\left(u_{0}(t)-c u_{0}(t-\delta)\right)^{\prime}+a(t) u_{0}(t) \leqslant c_{1} u_{0}\left(t-\tau_{1}\right)+\ldots+c_{n} u_{0}\left(t-\tau_{n}\right), \quad t \in \mathbb{R} .
$$

Integrating both sides of this inequality from 0 to $\omega$ and using the periodicity of $u_{0}$, we have

$$
\begin{aligned}
\int_{0}^{\omega} a(t) u_{0}(t) \mathrm{d} t & \leqslant c_{1} \int_{0}^{\omega} u_{0}\left(t-\tau_{1}\right) \mathrm{d} t+\ldots+c_{n} \int_{0}^{\omega} u_{0}\left(t-\tau_{n}\right) \mathrm{d} t \\
& =\left(c_{1}+\ldots+c_{n}\right) \int_{0}^{\omega} u_{0}(t) \mathrm{d} t
\end{aligned}
$$

From this it follows that

$$
\begin{equation*}
\underline{a} \int_{0}^{\omega} u_{0}(t) \mathrm{d} t \leqslant \int_{0}^{\omega} a(t) u_{0}(t) \mathrm{d} t \leqslant\left(c_{1}+\ldots+c_{n}\right) \int_{0}^{\omega} u_{0}(t) \mathrm{d} t . \tag{3.4}
\end{equation*}
$$

By the definition of cone $K, \int_{0}^{\omega} u_{0}(t) \mathrm{d} t \geqslant \alpha\left\|u_{0}\right\|_{C} \cdot \omega>0$. From (3.4) it follows that $\underline{a} \leqslant c_{1}+\ldots+c_{n}$, which contradicts the assumption in condition (F1). Hence $Q$ satisfies the condition of Lemma 2.6 in $K \cap \partial \Omega_{1}$. By Lemma 2.6, we have

$$
\begin{equation*}
i\left(Q, K \cap \Omega_{1}, K\right)=1 \tag{3.5}
\end{equation*}
$$

Next, choose $R>\max \{H / \alpha, \eta\}$, where $H$ is the positive constant in condition (F2), and let $e(t) \equiv 1$. Clearly, $e \in K \backslash\{\theta\}$. We show that $Q$ satisfies the condition of Lemma 2.7 in $K \cap \partial \Omega_{2}$, namely $u-Q u \neq \mu e$ for every $u \in K \cap \partial \Omega_{2}$ and $\mu \geqslant 0$. In fact, if there exist $u_{1} \in K \cap \partial \Omega_{2}$ and $\mu_{1} \geqslant 0$ such that $u_{1}-Q u_{1}=\mu_{1} e$, since $u_{1}-\mu_{1} e=Q u_{1}$, by definition of $Q$ and Lemma 2.4, $u_{1} \in C_{\omega}^{1}(\mathbb{R})$ satisfies the differential equation

$$
\begin{align*}
\left(u_{1}(t)-c u_{1}(t-\delta)\right)^{\prime}+a & (t)  \tag{3.6}\\
& \left(u_{1}(t)-\mu_{1}\right) \\
& =f\left(t, u_{1}\left(t-\tau_{1}\right), \ldots, u_{1}\left(t-\tau_{n}\right)\right), \quad t \in \mathbb{R}
\end{align*}
$$

Since $u_{1} \in K \cap \partial \Omega_{2}$, by the definition of $K$, we have

$$
\begin{equation*}
u_{1}\left(t-\tau_{k}\right) \geqslant \alpha\left\|u_{1}\right\|_{C}>H, \quad t \in \mathbb{R}, k=1, \ldots, n \tag{3.7}
\end{equation*}
$$

From this and condition (F2), it follows that

$$
f\left(t, u_{1}\left(t-\tau_{1}\right), \ldots, u_{1}\left(t-\tau_{n}\right)\right) \geqslant d_{1} u_{1}\left(t-\tau_{1}\right)+\ldots+d_{n} u_{n}\left(t-\tau_{n}\right), \quad t \in I
$$

By this inequality and (3.6), we have

$$
\left(u_{1}(t)-c u_{1}(t-\delta)\right)^{\prime}+a(t)\left(u_{1}(t)-\mu_{1}\right) \geqslant d_{1} u_{1}\left(t-\tau_{1}\right)+\ldots+d_{n} u_{1}\left(t-\tau_{n}\right), \quad t \in I
$$

Integrating this inequality on $[0, \omega]$ and using the periodicity of $u_{1}$, we have

$$
\begin{aligned}
\int_{0}^{\omega} a(t)\left(u_{1}(t)-\mu_{1}\right) \mathrm{d} t & \geqslant d_{1} \int_{0}^{\omega} u_{1}\left(t-\tau_{1}\right) \mathrm{d} t+\ldots+d_{n} \int_{0}^{\omega} u_{1}\left(t-\tau_{n}\right) \mathrm{d} t \\
& =\left(d_{1}+\ldots+d_{n}\right) \int_{0}^{\omega} u_{1}(t) \mathrm{d} t
\end{aligned}
$$

Consequently,

$$
\begin{align*}
\bar{a} \int_{0}^{\omega} u_{1}(t) \mathrm{d} t & \geqslant \int_{0}^{\omega} a(t) u_{1}(t) \mathrm{d} t \geqslant \int_{0}^{\omega} a(t)\left(u_{1}(t)-\mu_{1}\right) \mathrm{d} t  \tag{3.8}\\
& \geqslant\left(d_{1}+\ldots+d_{n}\right) \int_{0}^{\omega} u_{1}(t) \mathrm{d} t
\end{align*}
$$

Since $\int_{0}^{\omega} u_{1}(t) \mathrm{d} t \geqslant \alpha\left\|u_{1}\right\|_{C} \cdot \omega>0$, from this inequality it follows that $\bar{a} \geqslant$ $d_{1}+\ldots+d_{n}$, which contradicts the assumption in condition (F2). This means that $Q$ satisfies the condition of Lemma 2.7 in $K \cap \partial \Omega_{2}$. By Lemma 2.7,

$$
\begin{equation*}
i\left(Q, K \cap \Omega_{2}, K\right)=0 \tag{3.9}
\end{equation*}
$$

Now by the additivity of fixed point index, (3.5) and (3.9) we have

$$
i\left(Q, K \cap\left(\Omega_{2} \backslash \bar{\Omega}_{1}\right), K\right)=i\left(Q, K \cap \Omega_{2}, K\right)-i\left(Q, K \cap \Omega_{1}, K\right)=-1
$$

Hence $Q$ has a fixed point in $K \cap\left(\Omega_{2} \backslash \bar{\Omega}_{1}\right)$, which is a positive $\omega$-periodic solution of equation (1.1).

Pro of of Theorem 1.2. Let $\Omega_{1}, \Omega_{2} \subset C_{\omega}(\mathbb{R})$ be defined by (3.1). We prove that the operator $Q$ defined by (2.20) has a fixed point in $K \cap\left(\Omega_{2} \backslash \bar{\Omega}_{1}\right)$ if $r$ is small enough and $R$ large enough.

Let $r \in(0, \eta)$, where $\eta$ is the positive constant in condition (F3), and choose $e(t) \equiv 1$. We prove that $Q$ satisfies the condition of Lemma 2.7 in $K \cap \partial \Omega_{1}$, namely $u-Q u \neq \mu e$ for every $u \in K \cap \partial \Omega_{1}$ and $\mu \geqslant 0$. In fact, if there exist $u_{0} \in K \cap \partial \Omega_{1}$ and $\mu_{0} \geqslant 0$ such that $u_{0}-Q u_{0}=\mu_{0} e$, since $u_{0}-\mu_{0} e=Q u_{0}$, by definition of $Q$ and Lemma 2.4, $u_{0} \in C_{\omega}^{1}(\mathbb{R})$ satisfies the differential equation
(3.10) $\left(u_{0}(t)-c u_{0}(t-\delta)\right)^{\prime}+a(t)\left(u_{0}(t)-\mu_{0}\right)=f\left(t, u_{0}\left(t-\tau_{1}\right), \ldots, u_{0}\left(t-\tau_{n}\right)\right), \quad t \in \mathbb{R}$.

Since $u_{0} \in K \cap \partial \Omega_{1}$, by the definitions of $K$ and $\Omega_{1}, u_{0}$ satisfies (3.3). From (3.3) and condition (F3) it follows that

$$
f\left(t, u_{0}\left(t-\tau_{1}\right), \ldots, u_{0}\left(t-\tau_{n}\right)\right) \geqslant d_{1} u_{0}\left(t-\tau_{1}\right)+\ldots+d_{n} u_{0}\left(t-\tau_{n}\right), \quad t \in \mathbb{R}
$$

From this and (3.10), it follows that

$$
\left(u_{0}(t)-c u_{0}(t-\delta)\right)^{\prime}+a(t)\left(u_{0}(t)-\mu_{0}\right) \geqslant d_{1} u_{0}\left(t-\tau_{1}\right)+\ldots+d_{n} u_{0}\left(t-\tau_{n}\right), \quad t \in \mathbb{R} .
$$

Integrating this inequality on $[0, \omega]$ and using the periodicity of $u_{0}(t)$, we have that

$$
\begin{aligned}
\int_{0}^{\omega} a(t)\left(u_{0}(t)-\mu_{0}\right) \mathrm{d} t & \geqslant d_{1} \int_{0}^{\omega} u_{0}\left(t-\tau_{1}\right) \mathrm{d} t+\ldots+d_{n} \int_{0}^{\omega} u_{0}\left(t-\tau_{n}\right) \mathrm{d} t \\
& =\left(d_{1}+\ldots+d_{n}\right) \int_{0}^{\omega} u_{0}(t) \mathrm{d} t
\end{aligned}
$$

From this we obtain that

$$
\begin{align*}
\bar{a} \int_{0}^{\omega} u_{0}(t) \mathrm{d} t & \geqslant \int_{0}^{\omega} a(t) u_{0}(t) \mathrm{d} t \geqslant \int_{0}^{\omega} a(t)\left(u_{0}(t)-\mu_{0}\right) \mathrm{d} t  \tag{3.11}\\
& \geqslant\left(d_{1}+\ldots+d_{n}\right) \int_{0}^{\omega} u_{0}(t) \mathrm{d} s
\end{align*}
$$

Since $\int_{0}^{\omega} u_{0}(t) \mathrm{d} t \geqslant \alpha\left\|u_{0}\right\|_{C} \cdot \omega>0$, from the inequality (3.11) it follows that $\bar{a} \geqslant$ $d_{1}+\ldots+d_{n}$, which contradicts the assumption in (F3). Hence, $Q$ satisfies the condition of Lemma 2.7 in $K \cap \partial \Omega_{1}$. By Lemma 2.7, we have

$$
\begin{equation*}
i\left(Q, K \cap \Omega_{1}, K\right)=0 \tag{3.12}
\end{equation*}
$$

Then, choosing $R>\max \{H / \alpha, \eta\}$, we show that $Q$ satisfies the condition of Lemma 2.6 in $K \cap \partial \Omega_{2}$, namely $\lambda Q u \neq u$ for every $u \in K \cap \partial \Omega_{2}$ and $0<\lambda \leqslant 1$. In fact, if there exist $u_{1} \in K \cap \partial \Omega_{2}$ and $0<\lambda_{1} \leqslant 1$ such that $\lambda_{1} Q u_{1}=u_{1}$, then by the definition of $Q$ and Lemma 2.4, $u_{1} \in C_{\omega}^{1}(\mathbb{R})$ satisfies the differential equation
(3.13) $\left(u_{1}(t)-c u_{1}(t-\delta)\right)^{\prime}+a(t) u_{1}(t)=\lambda_{1} f\left(t, u_{1}\left(t-\tau_{1}\right), \ldots, u_{1}\left(t-\tau_{n}\right)\right), \quad t \in \mathbb{R}$.

Since $u_{1} \in K \cap \partial \Omega_{2}$, by the definition of $K$, $u_{1}$ satisfies (3.7). From (3.7) and condition (F4), it follows that

$$
f\left(t, u_{1}\left(t-\tau_{1}\right), \ldots, u_{1}\left(t-\tau_{n}\right)\right) \leqslant c_{1} u_{1}\left(t-\tau_{1}\right)+\ldots+c_{n} u_{1}\left(t-\tau_{n}\right), \quad t \in \mathbb{R}
$$

By this and (3.13), we have that

$$
\begin{equation*}
\left(u_{1}(t)-c u_{1}(t-\delta)\right)^{\prime}+a(t) u_{1}(t) \leqslant c_{1} u_{1}\left(t-\tau_{1}\right)+\ldots+c_{n} u_{1}\left(t-\tau_{n}\right), \quad t \in \mathbb{R} \tag{3.14}
\end{equation*}
$$

Integrating this inequality on $[0, \omega]$ and using the periodicity of $u_{1}(t)$, we have that

$$
\begin{aligned}
\int_{0}^{\omega} a(t) u_{1}(t) \mathrm{d} t & \leqslant c_{1} \int_{0}^{\omega} u_{1}\left(t-\tau_{1}\right) \mathrm{d} t+\ldots+c_{n} \int_{0}^{\omega} u_{1}\left(t-\tau_{n}\right) \mathrm{d} t \\
& =\left(c_{1}+\ldots+c_{n}\right) \int_{0}^{\omega} u_{1}(t) \mathrm{d} t
\end{aligned}
$$

From this we obtain that

$$
\begin{equation*}
\underline{a} \int_{0}^{\omega} u_{1}(t) \mathrm{d} t \leqslant \int_{0}^{\omega} a(t) u_{1}(t) \mathrm{d} t \leqslant\left(c_{1}+\ldots+c_{n}\right) \int_{0}^{\omega} u_{1}(t) \mathrm{d} t . \tag{3.15}
\end{equation*}
$$

Since $\int_{0}^{\omega} u_{1}(t) \mathrm{d} t \geqslant \alpha\left\|u_{0}\right\|_{C} \cdot \omega>0$, from the inequality (3.15) it follows that $\underline{a} \leqslant$ $c_{1}+\ldots+c_{n}$, which contradicts the assumption in condition (F4). Hence, $Q$ satisfies the condition of Lemma 2.6 in $K \cap \partial \Omega_{1}$. By Lemma 2.6, we have

$$
\begin{equation*}
i\left(Q, K \cap \Omega_{2}, K\right)=1 \tag{3.16}
\end{equation*}
$$

Now, from (3.12) and (3.16) it follows that

$$
i\left(Q, K \cap\left(\Omega_{2} \backslash \bar{\Omega}_{1}\right), K\right)=i\left(Q, K \cap \Omega_{2}, K\right)-i\left(Q, K \cap \Omega_{1}, K\right)=1
$$

Hence $Q$ has a fixed point in $K \cap\left(\Omega_{2} \backslash \bar{\Omega}_{1}\right)$, which is a positive $\omega$-periodic solution of equation (1.1).

## References

[1] K. Deimling: Nonlinear Functional Analysis. Springer, Berlin, 1985.
zbl MR doi
[2] H. I. Freedman, J. Wu: Periodic solutions of single-species models with periodic delay. SIAM J. Math. Anal. 23 (1992), 689-701.

Zbl MR doi
[3] D. Guo, V. Lakshmikantham: Nonlinear Problems in Abstract Cones. Notes and Reports in Mathematics in Science and Engineering 5. Academic Press, Boston, 1988.
zbl MR
[4] J. K. Hale: Theory of Functional Differential Equations. Applied Mathematical Sciences. Vol. 3. Springer, New York, 1977.
zbl MR doi
[5] L. Hatvani, T. Krisztin: On the existence of periodic solutions for linear inhomogeneous and quasilinear functional differential equations. J. Differ. Equations 97 (1992), 1-15.
zbl MR doi
[6] S. Kang, G. Zhang: Existence of nontrivial periodic solutions for first order functional differential equations. Appl. Math. Lett. 18 (2005), 101-107.
[7] Y. Kuang: Delay Differential Equations with Applications in Population Dynamics. Mathematics in Science and Engineering 191. Academic Press, Boston, 1993.
[8] Y. Luo, W. Wang, J. Shen: Existence of positive periodic solutions for two kinds of neutral functional differential equations. Appl. Math. Lett. 21 (2008), 581-587.
zbl MR doi
[9] J. Mallet-Paret, R.D. Nussbaum: Global continuation and asymptotic behavior for periodic solutions of a differential-delay equation. Ann. Math. Pure Appl. (4) 145 (1986), 33-128.
[10] E. Serra: Periodic solutions for some nonlinear differential-equations of neutral type. Nonlinear Anal., Theory Methods Appl. 17 (1991), 139-151.
zbl MR doi
[11] A. Wan, D. Jiang: Existence of positive periodic solutions for functional differential equations. Kyushu J. Math. 56 (2002), 193-202.
zbl MR doi [12] A. Wan, D. Jiang, X. Xu: A new existence theory for positive periodic solutions to functional differential equations. Comput. Math. Appl. 47 (2004), 1257-1262. (

Authors' address: Yongxiang Li, Ailan Liu, Department of Mathematics, Northwest Normal University, 967 Anning East Road, Lanzhou 730070, People's Republic of China, e-mail: liyxnwnu@163.com, 15339860773@163.com.

